Using Drool Rule-Platform for the Optical CAD Web-Application Development

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Abstract

This paper describes a development of rule-based web application to the problem of starting point selection in optical design. The system architecture is shortly discussed. A formalization of the optical system representation based on formal syntax is given. Three examples of rules in natural language and Drools Rule Language syntax illustrate the work of the solution.

Index terms: web application, rule-based system, Drools, optical design

I. INTRODUCTION

The design of optical systems (OS) is a sequential process including stages of the analysis of a technical specification, a structural synthesis, a parametric optimization etc. Currently there exists a lot of computer-aided design systems (CAD) that can effectively solve the problem of an optical scheme optimization (also known as parametric synthesis), calculating the exact parameters of an optical system. But for successful calculation of an optical system’s parameters the initial optical scheme or "starting point" for the whole design process must be specified correctly. Until now this problem is solved by an optical designer relying on his or her experience. At the same time, a special kind of software - expert systems (ES) are used successfully to solve design problems for several decades [1].

The selection of suitable starting point is one of the most important steps in the optical design and it in more than 80% determines the success of the whole project. A formal rule-based design method of structural synthesis shortly described in [2] was proposed by prof. M. Russinov and developed by I. Livshits. This makes it possible to create an expert system for the optical design.

II. MAIN PART

Due to the progress of expert system’s technology, there are plenty of rule platforms, which can be reused in a new development of expert system. When the complexity of the development is high, the right choice of effective tools acquires importance. Therefore we decided to choose the most effective platform that will suit to our purposes.

A. Selection of a rule platform

Before we started searching a suitable rule-platform we had defined general requirements of the platform to be complying with. The requirements are the following:

- advanced knowledge representation language (KRL);
- the support of traditional programming languages (PL);
the support of the forward chaining;
- the presence of tools for knowledge engineering and knowledge base development, such as a rule repository, a rule editor etc.;
- an Open Source license and an active developer’s community.

We reviewed a lot of platforms, but only the following comply with the requirements: OpenRules [6], Drools [7], OpenL Tablets [8] and CLIPS [9]. The results of the review are presented in Table I.

### Table I
THE COMPARISON OF THE RULE PLATFORMS

<table>
<thead>
<tr>
<th>Name</th>
<th>KRL</th>
<th>The support of traditional PL</th>
<th>The type of inference</th>
<th>The presence of tools for knowledge engineering</th>
<th>License</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpenRules</td>
<td>Tables (Excel, Rational DB), XML, POJOs</td>
<td>Java</td>
<td>the activation of rules depends on its order in the repository</td>
<td>rule editor, rule repository, version control</td>
<td>GPLv2, Commercial</td>
</tr>
<tr>
<td>OpenL Tablets</td>
<td>Tables (Excel, Word), Decision trees</td>
<td>Java</td>
<td>the activation of rules depends on its order in the repository</td>
<td>rule editor, rule repository, version control, decision tables</td>
<td>LGPL</td>
</tr>
<tr>
<td>Drools</td>
<td>DRL (Drools Rule Language), RuleML, CLIPS</td>
<td>Java</td>
<td>the forward and backward</td>
<td>rule editor, rule repository, version control, decision tables</td>
<td>ASLv2, Commercial</td>
</tr>
<tr>
<td>CLIPS</td>
<td>CLIPS</td>
<td>Python, C/C++, Java</td>
<td>only the forward</td>
<td>rule editor, version control</td>
<td>Public Domain</td>
</tr>
</tbody>
</table>

As it’s seen from the table, the all platforms have many ways to write rules (tables, own language etc.), tools for knowledge engineering and Open Source licenses, but only Drools Platform has both an advanced knowledge representation language and a powerful inference engine that can perform the forward and backward inference, whereby more complex expert system can be built.

**B. Overview of the system architecture**

By selecting the most appropriate rule platform, we have got the all needed tools for the development. Drools platform provides a powerful tool for knowledge engineering - Guvnor, containing different kinds of editors (such as a guided editor, a decision table editor), an integration testing framework, a storage of knowledge bases supporting versioning of rules, models etc. and a web-service giving an access to knowledge bases.

On Fig. 1 a conceptual diagram of the system architecture is present. As it’s seen from the diagram a user can work with the system either using a plain browser or via some external software communicating with the system through a web-service. All versions of knowledge bases are kept in the repository that is why the system has a separate module called knowledge agent connecting to the repository at the bootstrap stage of the system work and fetching the necessary version of the knowledge base to be used by inference engine.
A simple and effective formalization of the optical system representation based on formal syntax allows to build a description from the basic notions to the complex description, formulate consistent rules for the knowledge base, as well as expand the range of the problems of optical design, by introducing elements of the new features avoiding conflicts with an already used in the system.

The initial data for the starting point selection process are the technical requirements measured in physical units: Aperture speed, Angular field, Focal length, Angular units, Spectral range, Image quality, Wave units, Back focal distance, Entrance pupil position. However, for the rules of the knowledge base system it is more convenient to use generalized qualitative characteristics “0”, “1” or “2” and truth-value variables, inferred by the system. The conversion of the technical requirements to generalized values is present in Table II.

**TABLE II**

<table>
<thead>
<tr>
<th>Class</th>
<th>Characteristic</th>
<th>GVal “0”</th>
<th>GVal “1”</th>
<th>GVal “2”</th>
</tr>
</thead>
<tbody>
<tr>
<td>J</td>
<td>Aperture speed</td>
<td>OS is not fast &lt; 2.8</td>
<td>OS is fast 2.8 … 1.5</td>
<td>OS is super fast &gt; 1.5</td>
</tr>
<tr>
<td>W</td>
<td>Angular field</td>
<td>OS with small angular field &lt; 15°</td>
<td>OS with average angular field 15° … 60°</td>
<td>wide angular OS &gt; 60°</td>
</tr>
<tr>
<td>F</td>
<td>Focal length</td>
<td>short focal length OS &lt; 50 mm</td>
<td>average focal length OS 50 … 100 mm</td>
<td>long focal length OS &gt; 100 mm</td>
</tr>
<tr>
<td>L</td>
<td>Spectral range</td>
<td>monochromatic OS &lt; 5 nm</td>
<td>ordinary polychromatic 5nm … 200nm</td>
<td>super polychromatic correction &gt; 200 nm</td>
</tr>
<tr>
<td>Q</td>
<td>Image quality</td>
<td>“geometrical” image quality &gt; 5</td>
<td>“intermediate” image quality 2 … 5</td>
<td>“diffraction” image quality &lt; 2</td>
</tr>
<tr>
<td>S</td>
<td>Back focal distance</td>
<td>OS with short back focal length s &lt; ½f</td>
<td>OS with average back focal length 1/2f ≤ s ≤ f</td>
<td>OS with long back focal length s &gt; f</td>
</tr>
<tr>
<td>D</td>
<td>Entrance pupil position</td>
<td>entrance pupil located inside OS</td>
<td>removed back entrance pupil</td>
<td>removed forward entrance pupil</td>
</tr>
</tbody>
</table>
A superposition notation is used for a formal description of the optical system scheme as a sequence of elements «OE1 + OE2 + OE3 + ...». Each element is represented by a type symbol and a list of surfaces. A generic notation of an element is nexxs, where n, x - numbers, e - type of element, s - type of surfaces.

A type of an element can be “B” - Basic Elements, “C” - Correction Elements, “T” - Fast Elements or “Y” - Wide-angular Elements. A type of surfaces is selected from “O” - a flat surface, “P” - a surface concentrated the center of the input pupil, “A” - an aplanatic surface, “F” - a surface concentrated the focus, “I” - a surface located near the focal zone, “V” - a variable surface. The variety of number of surfaces depends on a construction of the element. For example for lenses the list includes two records. But for other types of optical elements the list may consist of one record, if the element is a mirror, or 3 or more for elements with a complex structure.

Finally a description of the optical surface consists of specifying the zone where it is located and the type of surface. Location of the surfaces can be “1”- before aperture, “2”- near aperture, “3” - near image.

Formal representation syntax for optical system scheme in Backus–Naur Form is given below:

```
OS ::= <Y>" + "<B>" + "<T>" + "<C>

<Y> ::= "" | <Y_expr> | <Y_expr><C>

<Y_expr> ::= <numbers_elements>"Y"<surface_list>

<B> ::= <B_expr> | <B_expr><C>

<B_expr> ::= <numbers_elements>"B"<surface_list>

<T> ::= "" | <T_expr> | <T_expr><C>

<T_expr> ::= <numbers_elements>"T"<surface_list>

<C> ::= "" | <C_expr>

<C_expr> ::= <numbers_elements>"C"<surface_list>

<numbers_elements> ::= "" | "2" | "3" | "4" | "5"

<surface_list> ::= <surface><surface>

<surface> ::= <zone><surface_type>

<zone> ::= "1" | "2" | "3"

<surface_type> ::= "O" | "P" | "A" | "F" | "I" | "V"
```

An example of a starting point description according with proposed syntax is “Y3P3P + B3A3P + C3I3I”.

D. Examples of rules

The rules have the following format: IF <conditions> THEN <actions>. Below are examples of three rules from the knowledge base. The first one is an example of conversion of the technical requirement of an aperture speed to a generalized value “OS is fast”.

The rule in the natural language:

```
IF
the aperture speed of the OS between 2.8 and 1.5

THEN
classify the OS as a fast and set the J class with the value equals “1”
```

And the same rule in the DRL (Drools Rule Language) that is used in our knowledge base as a knowledge representation language:

```
declare Classification
J : int
W : int
```

```
IF
the aperture speed of the OS between 2.8 and 1.5
THEN
classify the OS as a fast and set the J class with the value equals “1”
```
... declare Requirements
  apertureSpeed : float
  focalDistance : float
... end

rule “Classify as fast”
  when
    $class := Classification()
    Requirements( apertureSpeed < 2.8 && > 1.5 )
  then
    modify( $class ){
      setJ( 1 )
    }
end

Here we declare two new types of data. The first with name “Requirements” represents the technical requirements; the second “Classification” represents the classification of the OS and a rule with name “Classify as fast”. The Requirements type has fields apertureSpeed, focalDistance etc. And the Classification type has fields J, W etc. representing the classes.

The second is an example of reasoning on a meta level as we exclude from the starting point inference all rules concerning fast optical elements. The rule in the natural language:

IF
  the optical system is not fast
THEN
  a fast element isn’t needed at the system

And the same meta-rule in the DRL:

declare SystemConditions
  isFastNeeded : boolean
  isWideAngleNeeded : boolean
... end

rule “No fast”
  when
    Classification( J == 1 )
    $conds := SystemConditions()
  then
    modify( $conds ) {
      setIsFastNeeded( false )
    }
end

Here we declare one more type of data. It’s “SystemConditions” representing inferred conditions for another rules and a rule with name “No fast”. The SystemConditions type has fields isFastNeeded, isWideAngleNeeded etc. The “No fast” rule will be activated when the working memory contains an instance of the Classification type with the value of the field J equals ‘1’ and then the value of the isFastNeeded field of an SystemConditions’ instance will be set to ‘false’.
The last rule is a plain rule as we select only the ‘B3A3P’ base element.
The rule in natural language:
IF
the entrance pupil of an optical system is removed forward
THEN
exclude the all base elements with exception of B3A3P element

The same but only in the DRL syntax is:

```
declare OpticalElement
type : String
surfaces: String
...
end

rule “The B3A3P element”
when
Classification( D == 2 )
$elements := ArrayList() from collect( OpticalElement() )
then
modify( $elements ) {
clear()
add( new OpticalElement( type == “B”,
surfaces == “3A3P” ))
}
end
```

At this example we declare a new type “OpticalElement” representing an optical element and the “The B3A3P element” rule that will be fired when an instance of Classification type with the value of the D field equals to 2.

III. CONCLUSION

In the optical design process there is a specific stage - a starting point selection or structural synthesis of an optical system scheme. There are no appropriate software solutions for this stage. But it is well known that a rule based approach has proved its effectiveness for such a task. Authors describe an approach to development of rule-based web application for the optical design. As a platform Drools is used. The selection of the platform is based on rule-engines’ review. Also a knowledge formalization of optical design data is made. This formalization make it possible to formulate rules in user-friendly manner. But in fact the proposed approach is opened for extension and rules for other types of optical systems can be added into the knowledge base. We also plan to develop a special user interface to be used in designers’ training and integrate our system with optical optimization software.

REFERENCES